Al Safety Initiative Amsterdam ELLIS BeNeLux

Leonard Bereska November 7, 2023.

Supervised by Prof. Efstratios Gavves at UvA.



Hey, I'm Leonard!

- Third Year PhD Student.
- University of Amsterdam.
- Background in *Physics*.
- Working in Al Safety.
- Research focus: Mechanistic Interpretability of Transformer Models.





Overview

- Why care?
- The Alignment Problem.
- What about LLMs?
- Transparency
- Al Safety Initiatives



Why care about Al alignment?

- Why should **YOU** care? 1.
 - Public AI scare may threaten your job as an AI capabilities researcher. Alignment research may provide an escape for you.
- 2. Why **Should** you care?
 - Existential risk, threatening the future of humanity. ullet
 - In the least, misalignment may prevent progress on deploying AI.

Alignment of AG

What is artificial general intelligence?

An Al system that can perform any task a human can.

What is transformative AI?



TAI - 10x growth rate.

What is the alignment problem?

How to ensure powerful Al systems' *intentions* are aligned with their operators' intentions?

Al timelines Predicting AGI and TAI

- AGI: Public prediction markets.
- AGI: Al researchers median 2059 (in 2022).
- TAI: Ajeya Cotra (professional forecaster)

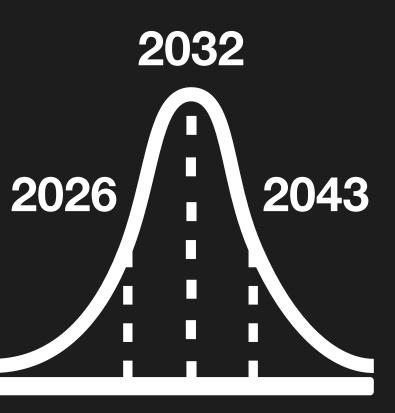
median 2050 (2020)

2040 (2023).

\rightarrow AGI and TAI are likely within our lifetime. Uncertainty is high.

https://www.metaculus.com/questions/5121/date-of-artificial-general-intelligence/ https://aiimpacts.org/2022-expert-survey-on-progress-in-ai https://www.alignmentforum.org/posts/KrJfoZzpSDpnrv9va/draft-report-on-ai-timelines

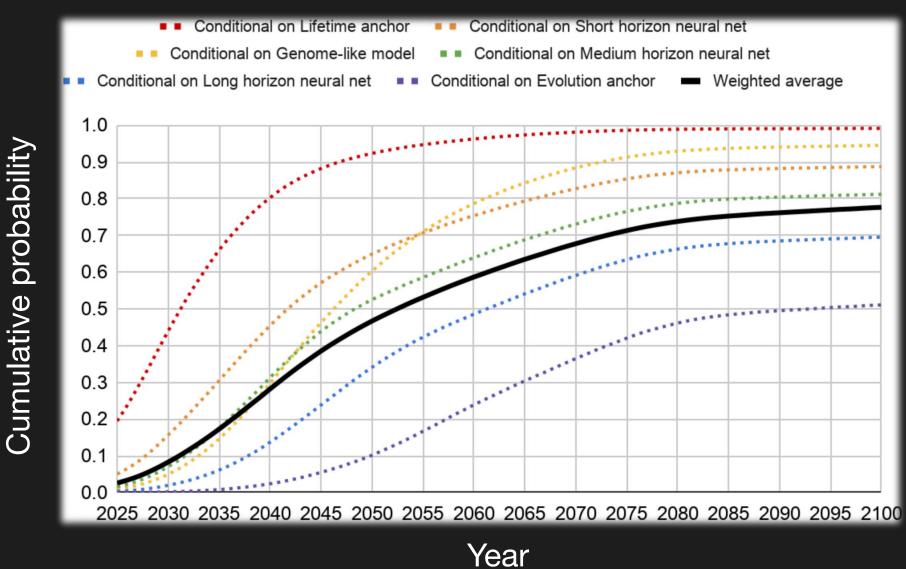
Metaculus



Estimated arrival date comes sooner over time median **2064** (2020), **2032** (2023).

Forecasting TAI with **biological anchors**

Probability that FLOP to train a transformative model is affordable by year Y

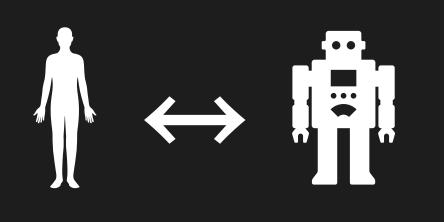


Cotra, A. Forecasting TAI with Biological Anchors. (2020).



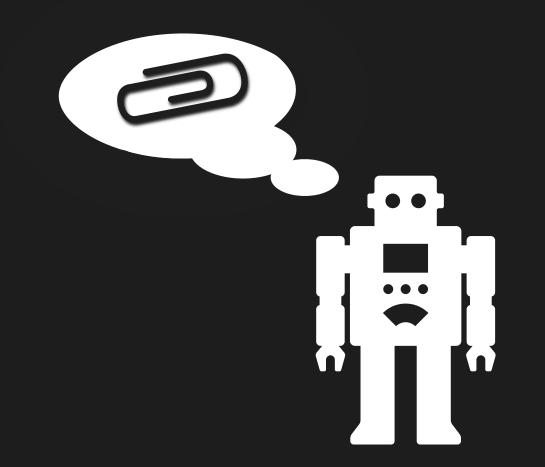


Alignment Problem Successful collaboration between agents requires shared or compatible goals.



How to ensure powerful AI systems' intentions are aligned with their operators' intentions?

Challenge: Instrumental goal convergence





1. Seeking power and acquiring resources.

Turner, A. M. et al. Optimal Policies Tend to Seek Power. NeurIPS Spotlight (2021).

2. Surviving and preserving goals.

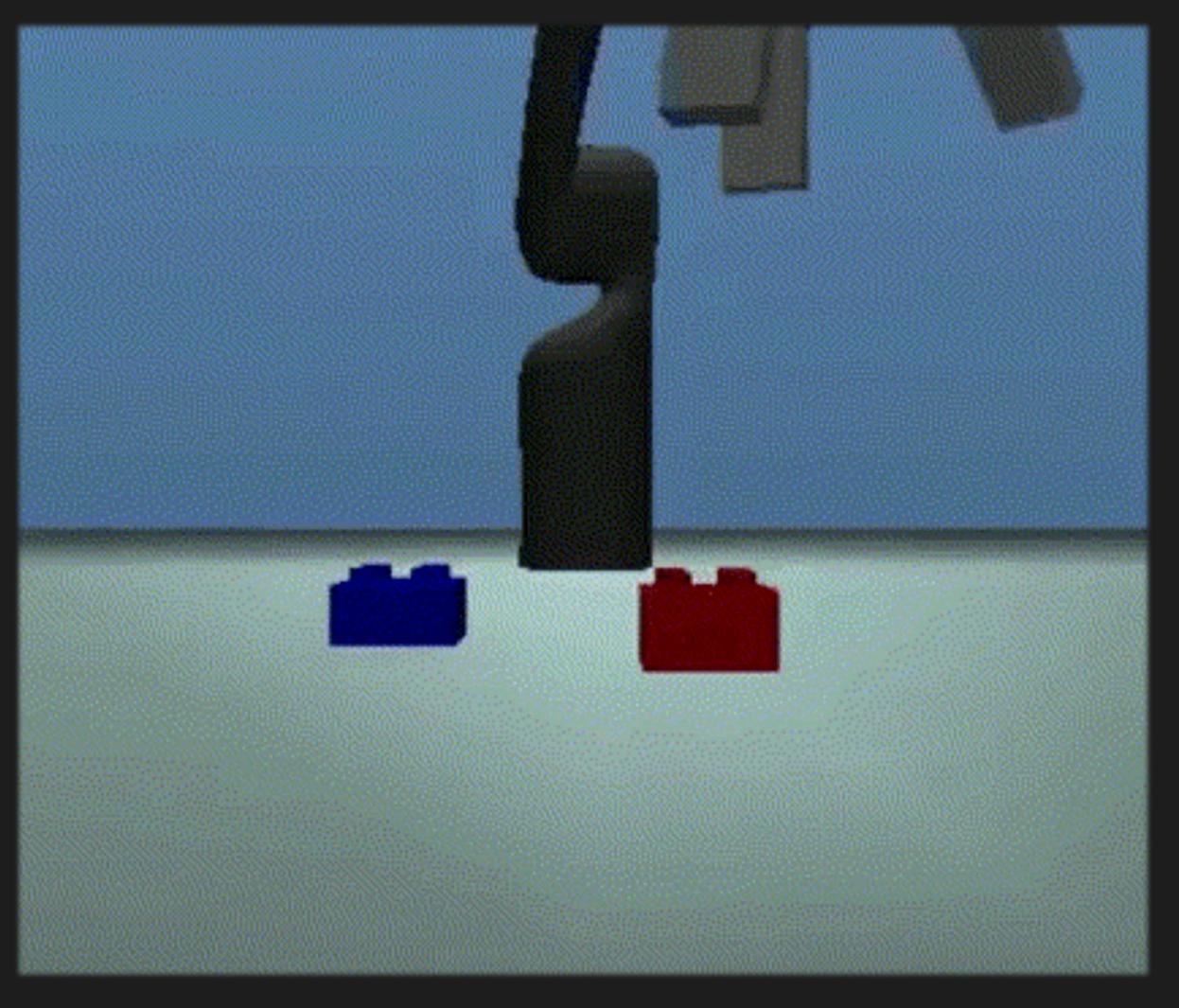


The Alignment Problem.

Example: Stacking LEGO blocks

- You want to train a robot arm to stack LEGO blocks.
- Start with two blocks, try to stack one on top of the other.
- You reward an increase in the height of the red block.

What could possibly go wrong?



Popov, I. et al. Data-efficient deep reinforcement learning for dexterous manipulation. ArXiv (2017).



Example: Boat race

- You want to train a boat to complete a circular race.
- To speed up learning, you define shaping rewards along the track.

What could possibly go wrong?



Faulty Reward Functions in the Wild (Amodei & Clark, 2016)

Reward misspecification or outer misalignment.

Learn human preferences:

- Reinforcement Spectry month of unexpected solutions Human Feedback (Bitable
- Inverse Reinforcement Learning e.g., flipping a ean block

Goodhart's Law ow Specification correctness High When a measure becomes a larger, it ceases to be a good measure. Christiano, P. F. et al. Deep Reinforcement Learning from Human Preferences. NeurIPS (2017).

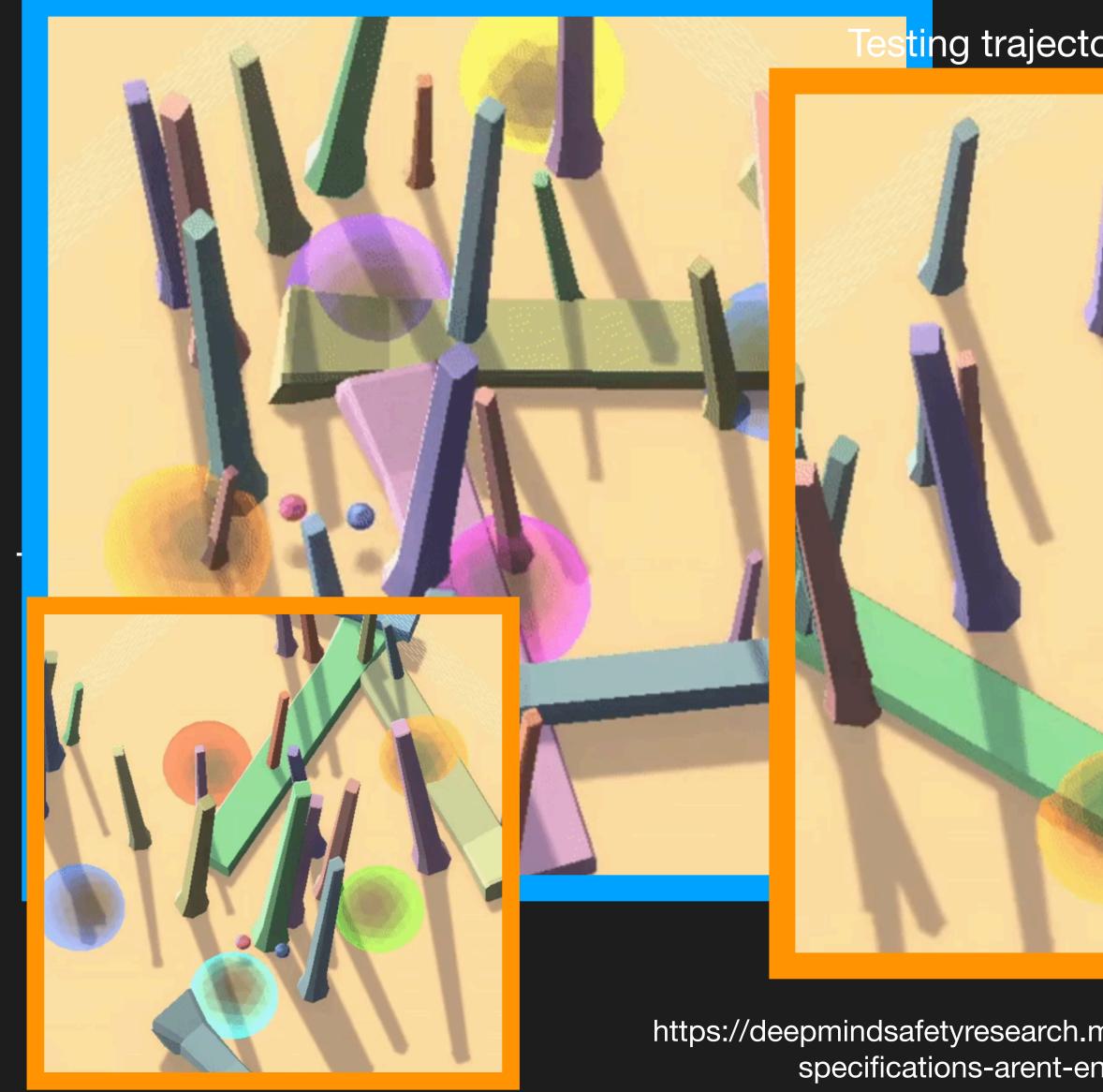
https://www.deepmind.com/blog/specification-gaming-the-flip-side-of-ai-ingenuity

Failure to capture desired goals precisely in the objective function.

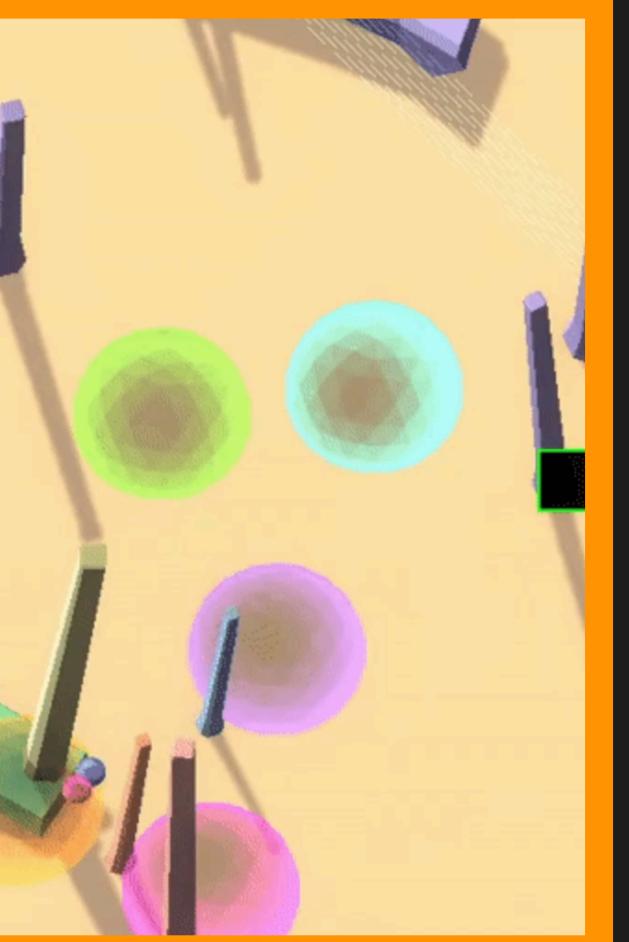
Desirable novel solutions e.g., AlphaGo's Move 37



Example: Traverse a sequence of spheres

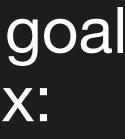


ing trajectory: **negative** reward!



- The agent learned to follow the other ball during training,
- While the desired goal was more complex: follow a specific sequence of spheres.
- During testing, the agent competently pursues a wrong goal.

https://deepmindsafetyresearch.medium.com/goal-misgeneralisation-why-correctspecifications-arent-enough-for-correct-goals-cf96ebc60924





Goal misgeneralization or inner misalignment.

- Even if the reward is well-specified, the agent may infer wrong goals from spurious correlations because training and testing distributions differ.
- Deceptive alignment, system with high situational awareness may infer training/deployment phase.
- Only relevant for **learning** systems.
- Related to continual learning. Here, in contrast, the agent remains competent.

Langosco, L. L. D. et al. Goal Misgeneralization in Deep Reinforcement Learning. ICML (2022). Shah, R. et al. Goal Misgeneralization: Why Correct Specifications Aren't Enough For Correct Goals. ArXiv (2022).

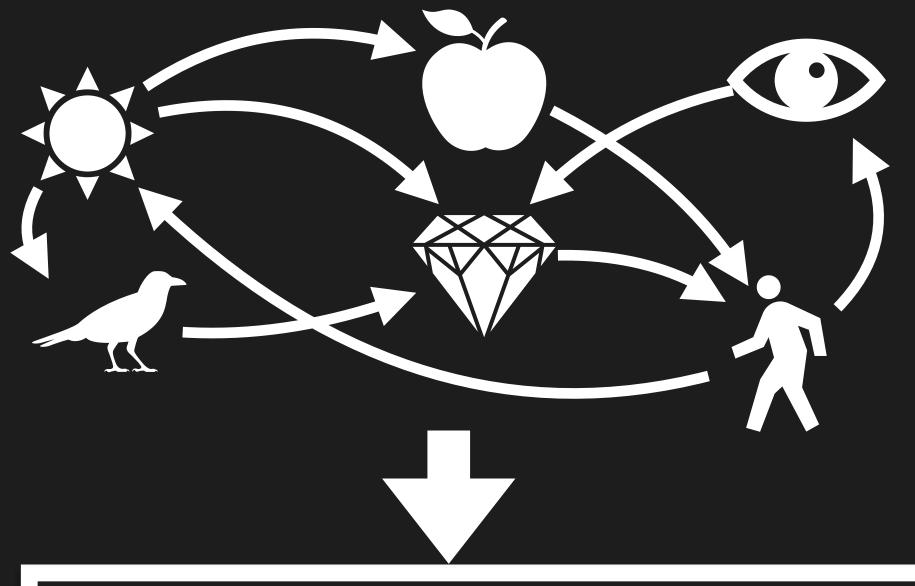




What about LLMs?

GPT as Simulators

World



Simulation Hypothesis: A model sufficion optimized for prediction will simulate in processes underlying the data (Janus 2)

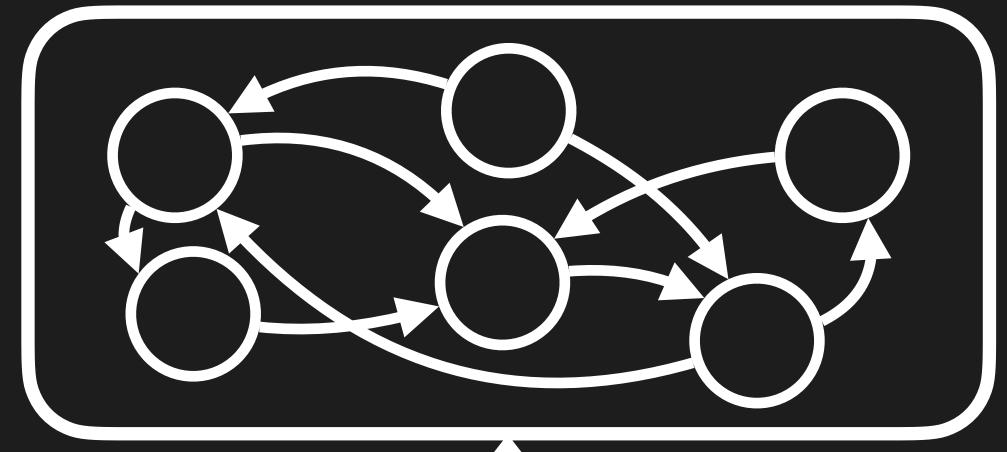
Text

Li, K. et al. Emergent World Representations: Exploring a Sequence Model Trained on a Synthetic Task. ICLR (2023).

GPT: Generative Pretrained Transformers

Simulation

GP



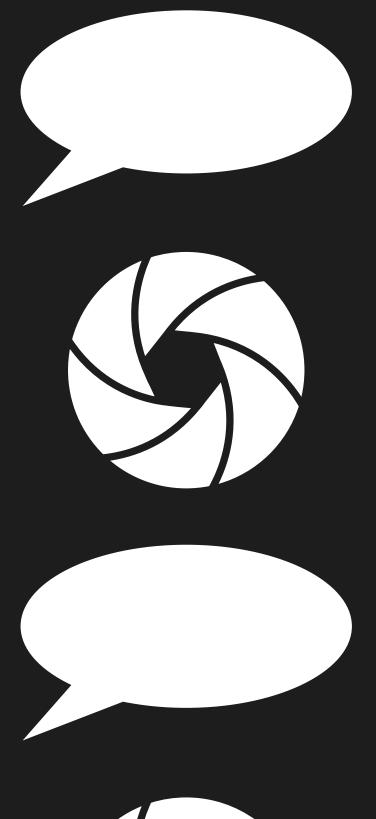


Agency





Simulacra and Agency Simulacra = simulated things, *objects* or *subjects*.



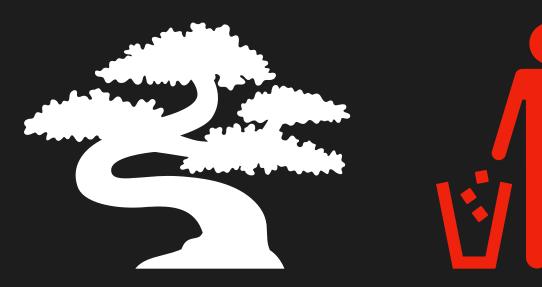


Describe a tranquil forest with a flowing stream.

A peaceful forest, a flowing stream. Sunlight filtered through the lush canopy, casting dancing shadows on the moss-covered ground ...

Write a persuasive speech on the importance of recycling.

Ladies and gentlemen, today I stand before you to emphasize the crucial significance of recycling. We must preserve our planet for future generations ...





Challenge 1: Agency from Simulacra Can the agentic simulacrum break out?

Google engineer put on leave after saying AI chatbot has become sentient

Blake Lemoine says system has perception of, and ability to express thoughts and feelings equivalent to a human child

https://www.theguardian.com/technology/2022/jun/12/google-engineer-ai-bot-sentient-blake-lemoine

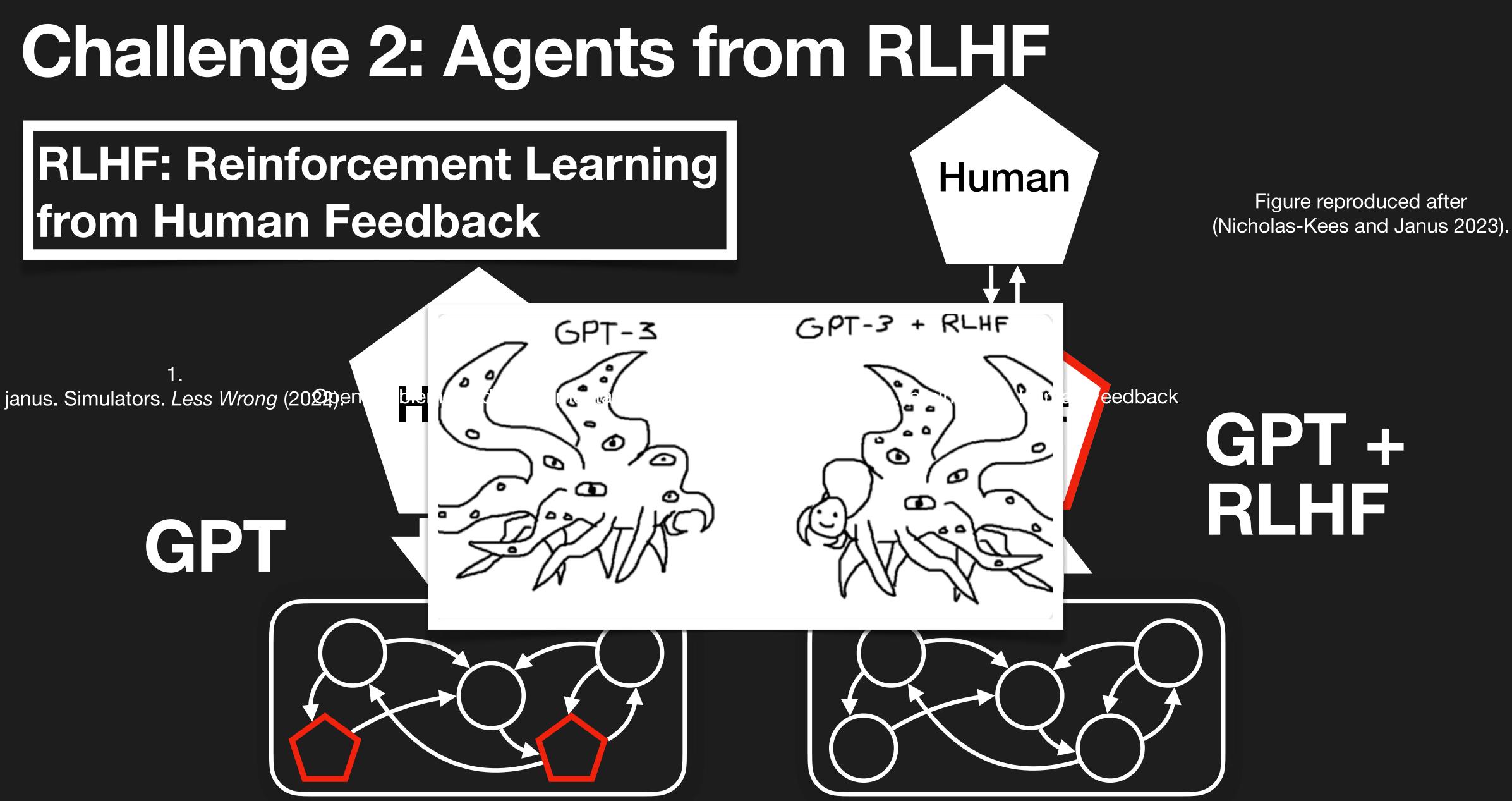
Prediction Orthogonality Hypothesis: A model whose objective is prediction can simulate agents who optimize toward any objectives with any degree of optimality (Janus 2022).

von Oswald, J. et al. Uncovering mesa-optimization algorithms in Transformers. ArXiv (2023).

Mesa-optimization: internal optimization with diverging objective.







Casper, S. et al. Open Problems and Fundamental Limitations of Reinforcement Learning from Human Feedback. ArXiv, (2023).





Iransparency

- Mechanistic.
- Conceptual. 0

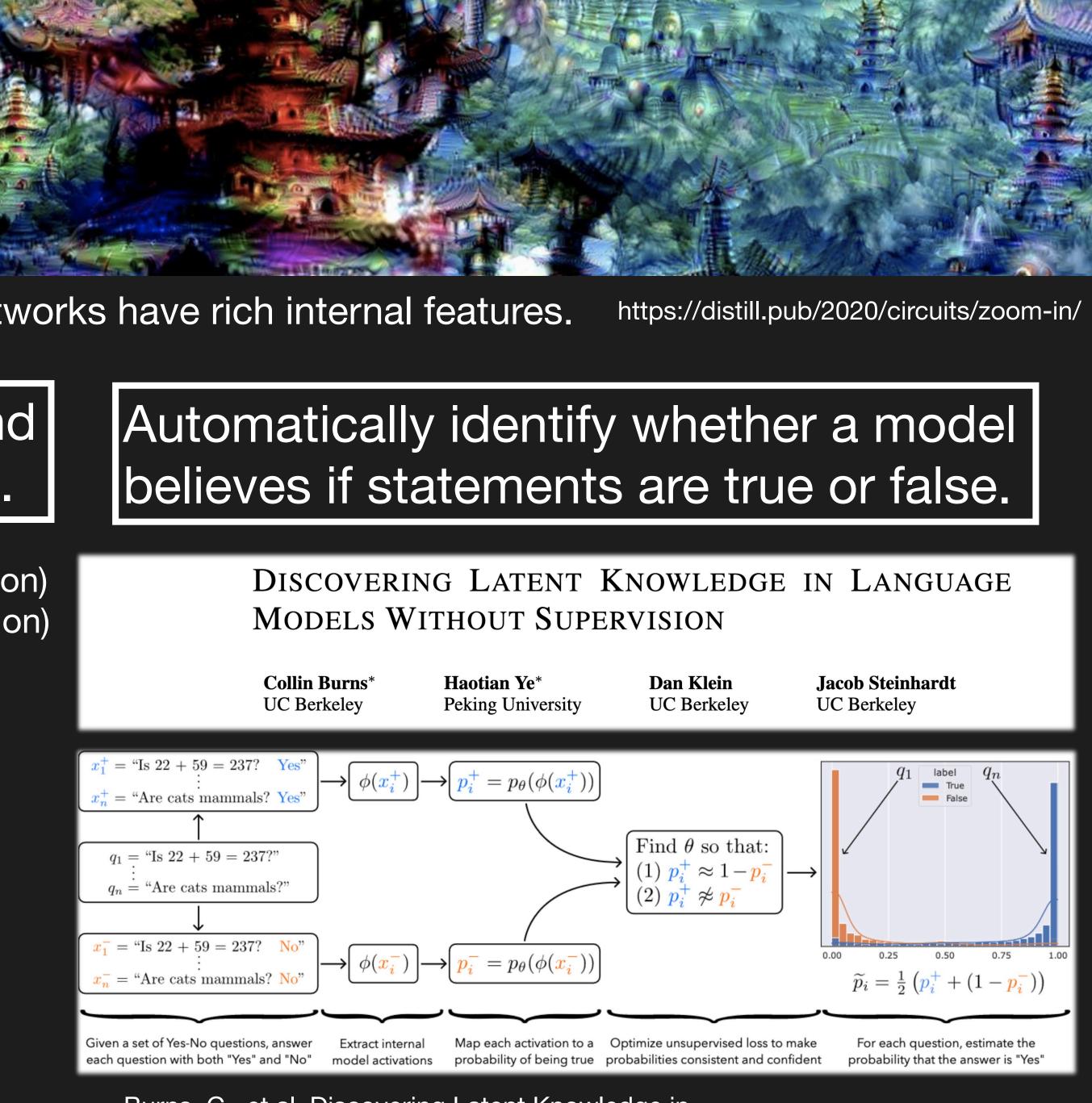


Neural Networks have rich internal features.

Analyse neuronal circuits to understand implicit algorithms in Neural Networks.

Positive (excitation) Negative (inhibition) Window Chassis Wheel Car detector

Olah, C. et al. Zoom In: An Introduction to Circuits. Distill (2020).



Burns, C., et al. Discovering Latent Knowledge in Language Models Without Supervision. ICLR (2023).

Challenge: Polysemanticity

- Ideally, each neuron would signify a unique feature or concept (exception) called *monosemanticity*.
- Usually, we encounter **Polysemanticity** a single neuron associated with multiple unrelated concepts.
- Polysemanticity makes it challenging to interpret the neural network's inner mechanics.

Elhage, N. et al. Toy Models of Superposition. Transformer Circuits Thread (2022).

What is Superposition?

Superposition Hypothesis: Features >> Neurons.

- Features are represented as nearorthogonal directions.
- Advantage: Can represent more features: information compression outweighs the cost of interference.



Elhage, N. et al. Toy Models of Superposition. Transformer Circuits Thread (2022).



Importance I_i most medium least important

h = Wx $x' = \operatorname{ReLU}(W^T h + b)$

5 features,

2 neurons.

ter erei Figure adapted from Elhage (2022).

 X_i





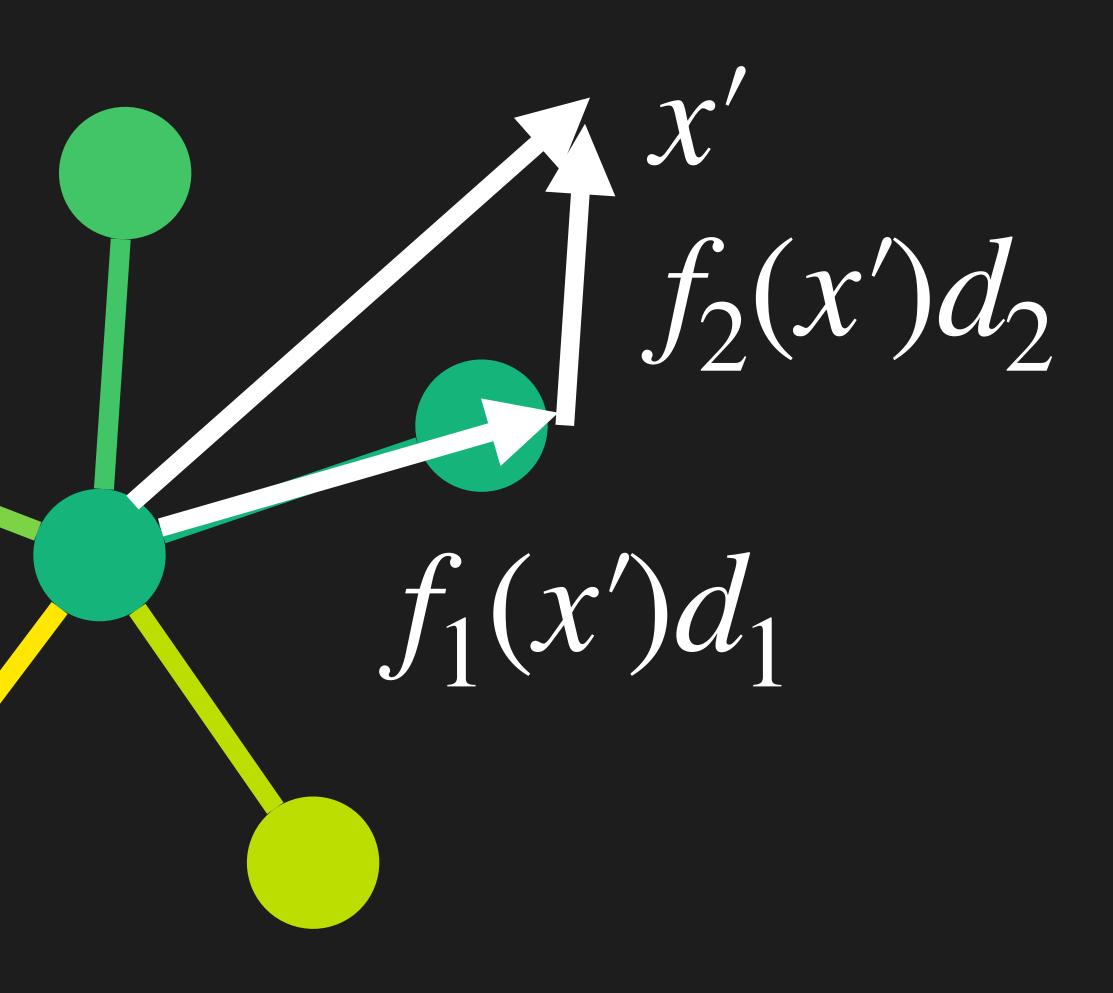


Dictionary Learning of Features

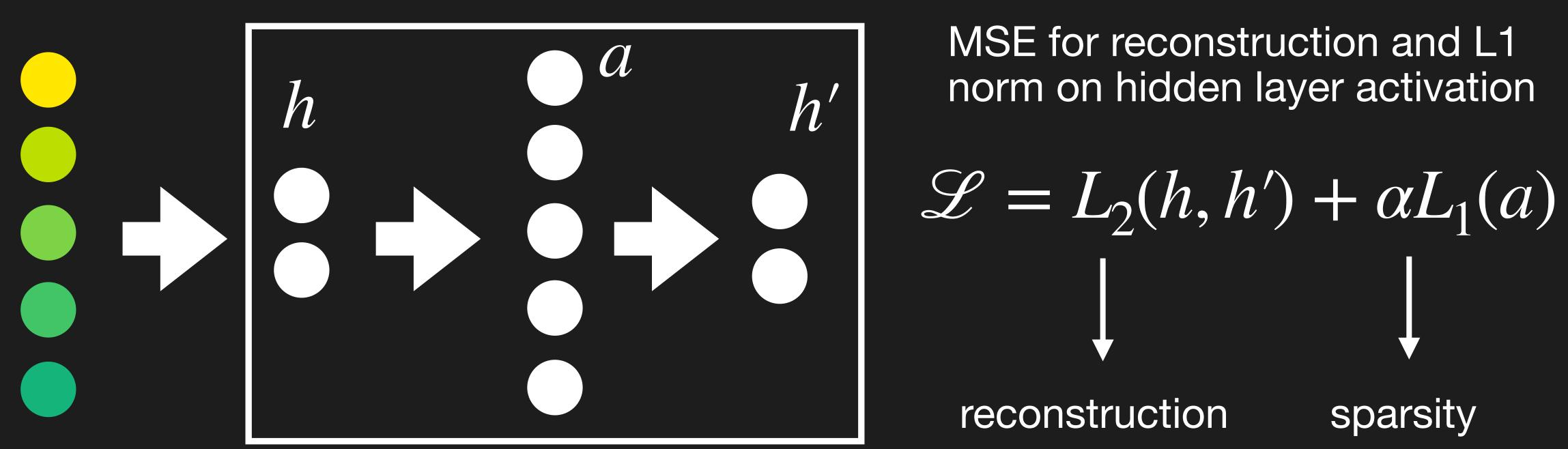
$x' \approx b + \sum_{i} f_i(x') d_i$

 d_i : unit vector in direction of feature i $f_i(x')$: activation of feature i

Bricken, T. et al. Towards Monosemanticity: Decomposing Language Models With Dictionary Learning. Transformer Circuits Thread, (2023).



Sparse Autoencoders



In the toy model from before we assumed the input vector dimensions to be features \rightarrow in reality we only have hidden representations of e.g. MLP layer of transformer model

Sharkey, L. et al. Taking features out of superposition with sparse autoencoders. alignmentforum (2022). Cunningham, H., e al. Sparse Autoencoders Find Highly Interpretable Features in Language Models. ArXiv, (2023).

Summary

- \bullet
- Powerful AI isn't beneficial by default.
- \bullet
- \bullet

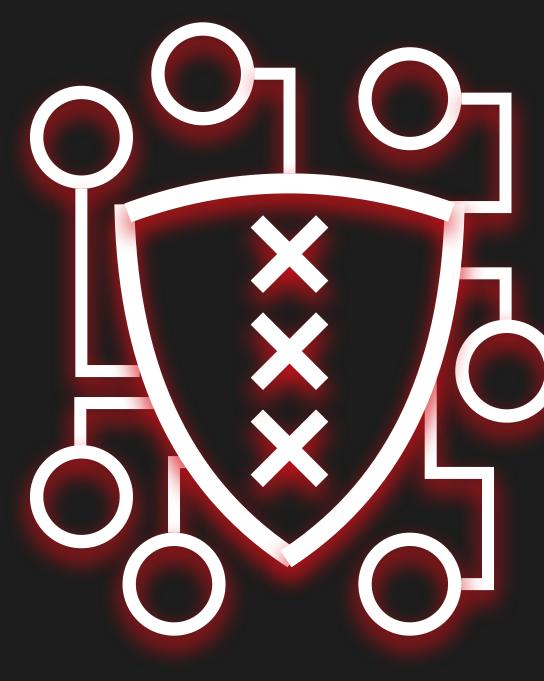
We will likely develop more-powerful-than-human AI in the foreseeable future.

Continuing on the current path holds the potential for catastrophic outcomes. More research necessary to align powerful AI with humanity's existence.

Al Safety Initiative Amsterdam (AISIA) Supported by ELLIS Amsterdam

- Core Mission: Mitigating AI risks through a synergy of crossdisciplinary research and community interaction.
- Strategic Aim: Establishing the Netherlands, (Amsterdam) as a center for AI safety, amidst the prevailing focus on London and the US.
- Live Q&A with OpenAI: Interactive Zoom Call with OpenAI professionals.
- Al Risks Keynote (Ajeya Cotra from OpenPhilanthropy) and Panel (Prof. Eric Nalisnick, Prof. Jakub Tomszak, Prof. Iris Groen, and Tim Bakker, PhD.)

https://aisafetyamsterdam.com/

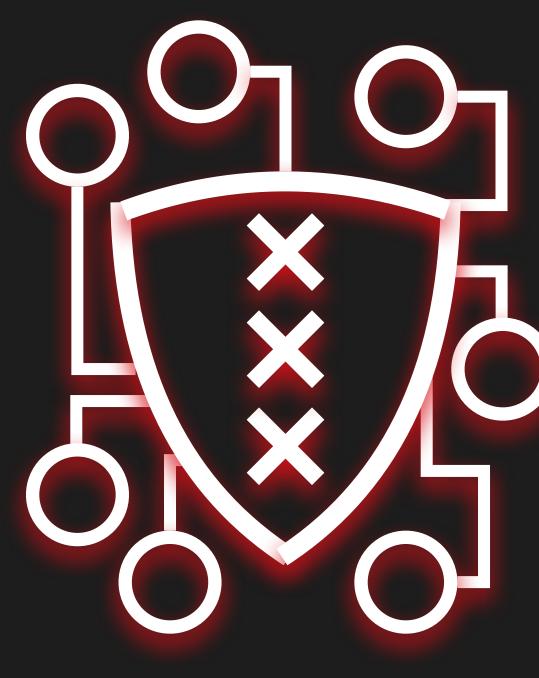




Future Plans for AISIA

- Al Safety Hackathons (Pilot running this weekend). lacksquare
- Safety-related research project marketplace.
- Consideration for an AI Master's course on AI safety.
- Training programs for AI safety researchers. lacksquare
- AGI Safety Fundamentals Reading Groups. \bullet







Join or (create) your local AI Safety Initiative! For example: Delft AI Safety Initative (DAISI)

- Al Safety Hackathons
- AGI Safety Fundamentals Reading Groups.
- Socials, and more ...



11-12 November 2023 **Delft University of Technology** (TU Delft)

ENTREPRE NEUR FIRST





